## SCHEME OF INSTRUCTION AND EXAMINATION B.E III YEAR Electrical and Electronics Engineering

# SEMESTER-I

	Course Code	Course Title	Scheme of Instruction Periods per Week		Scheme of Examination		
SI. No					Durati on in	Maximum Marks	
			L/T	D/P	Hours	Sessionals	University Exam
1.	EE 301	Power Systems – II	4	-	3	25	75
2.	EE 302	Electrical Machinery – II	4/1	-	3	25	75
3.	EE 303	Power Electronics	4/1	-	3	25	75
4.	EE 304	Digital Electronics and Logic Design	4	-	3	25	75
5.	EE 305	Linear Integrated Circuits	4	-	3	25	75
6.	EE 306	Linear Control Systems	4/1	-	3	25	75
7.	EE 331	Electrical Machines Lab-I	-	3	3	25	50
8.	EE 332	Control Systems Lab	-	3	3	25	50
		Total	24/3	6	-	200	550

## **POWER SYSTEMS-II**

Instruction	:	4 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	75 Marks

## **Objectives:**

- 1. The student should be able to learn and understand the performance analysis of transmission lines and cables.
- 2. To be able to comprehend analysis of symmetrical and unsymmetrical faults in the power system.

## UNIT-I

**Transmission Line theory:** Short, medium, long lines- Line calculations, surge Impedance Loading, Tuned Lines-Power Circle Diagrams and their applications. Corona: Causes- Disruptive and Visual Critical Voltages, Power loss -minimization of Corona effects.

## UNIT-II

**Voltage Control:** Phase Modifiers, Induction Regulators -Tap Changing Transformers, Series and Shunt Capacitance. Reactive Power Requirement Calculations. Static Var Compensators-Thyristor Controlled Reactors- Thyristor Switched Capacitors.

## UNIT-III

**Per Unit System of Representation:** Use of per unit quantities in power systems, Advantages of per unit system. Symmetrical Three Phase transients in R-L series circuits-Short Circuit Currents - Reactance of Synchronous Machines- Symmetrical Fault Calculations. Single line diagram – Impedance - reactance diagram. Short circuit capacity of a bus

### UNIT-IV

**Unsymmetrical Faults:** Symmetrical components of unsymmetrical phasors -Power in terms of symmetrical components -sequence impedance and sequence networks. Sequence networks of unloaded generators - Sequence impedances of circuit elements - Single line to ground, line-to-line and double line to ground faults on unloaded generator-Unsymmetrical faults of power systems.

### UNIT-V

**Transients in Power Systems:** Causes of over voltages. Travelling Wave ; Theory - Wave equation -Open Circuited Line -The short circuited line Junction of lines of different natural impedances- -Reflection and refraction Coefficients -Junction of Cable and overhead lines -Junction of three lines of different natural impedances -Bewley Lattice diagram.

- 1. C.L. Wadhwa, *Electrical Power Systems*, Wiley Eastern Ltd., 4dtEdition, 2006.
- 2. John J. Grainger William D.Stevenson Jr., *Power System Analysis*, Tata McGraw Hill Edn. 2003
- 3. I.J. Nagrath & D.P.Kothari, Modern Power Systems Analysis, TMH Edition, 2003.
- 4. A.Chakrabarti, M.L.Soni, P. V.Gupta, U.S.Bhatnagar, *A Text book on Power System*, Dhanpat Rai & Co (P) Ltd -1999.

## **ELECTRICAL MACHINERY-II**

Instruction	:	4/1 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	75 Marks

### **Objectives:**

- 1. To be able to understand in detail about transformers and induction machines. Construction, principle, performance characteristics and testing.
- 2. To understand the construction, principle and performance characteristics of fractional HP motors

## UNIT-I

**Three phase Transformers** :Three phase Transformer Connections ,Choice of Transformer Connections, Third harmonic voltages -Phase Conversion 3-phase to 2-phase transformation - Scott connection. Constructional features of three-phase transformers, tertiary winding, parallel operation of transformer, Auto Transformer -Comparison with two winding transformers-Conversion of two winding transformer to auto transformer. Tap changer on transformers, No-load tap changer.

### UNIT-II

**Three phase Transformers** :Parallel operation of Single phase Transformer and load sharing. Insulation of Windings and terminals. Cooling arrangement in Transformers. Testing of Transformers -Routine Tests and Special tests -Measurement of Voltage ratio and check for voltage vector relationship. Measurement of No- load loss and current. Measurement of Insulation resistance. Maintenance of Transformers.

## UNIT-III

**Three-phase Induction Motor** -Constructional features –Rotating Magnetic field theory –-Principle of operation of squirrel cage and slip ring motors -Vector Diagram, Equivalent circuit -Expression for torque- Starting torque, Maximum torque -Slip/Torque characteristics, modes of operation - Performance characteristics -Equivalent circuits from test –Current loci circle diagram -Predetermination of characteristics of Induction Motors .

### UNIT-IV

**Three-phase Induction Motor** : Starting methods of Induction motors, torque and power limits of Induction motors-Speed control methods -Resistance Control, Voltage control, pole changing, Cascading, variable frequency control- Slip power recovery schemes - Double cage Induction motors. Induction generator

### UNIT-V

**Unbalanced Operation:** Voltage Unbalance -Unbalanced Operation of 3- phase Induction Motor -Per Phase Equivalent Circuits -Single Phasing- Unbalanced Operation of 3-Phase Transformers –Single phase load on Three phase transformers Single Phasing in 3 phase transformers- Delta /Star and Star/Delta transformers.

#### Suggested Reading:

1. I.J. Nagarath, D.p.Kothari, *Electrical Machines*. 4<sup>th</sup> Edition Tata McGraw Hill, 2010.

2. J.B. Gupta, Theory and Performance of Electrical Machines, S.K. Kataria. & Sons, 2003.

- 3. P.S. Bimbhra, Generalised theory of Electrical Machines, Khanna Publishers Fifth Edition 1995
- 4. M.G.Say, The performance and Design of A.C. Machines- Pitman, 1985.
- 5. Fitzerald A E and Kingzley, *Electrical Machines*. 3rd Edition.

### POWER ELECTRONICS (Common to IE & EEE)

:	4/1 Periods per week
:	3 Hours
:	25 Marks
:	75 Marks
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### **Objectives:**

- 1. To be able to understand various power switching devices, characteristics and applications.
- 2. To learn and understand the various converters like rectifiers, choppers and inverters principle operation, characteristics and applications.

### UNIT-I

**Power Semiconductor Diodes and Transistors:** Types of power diodes- General purpose diodes -Fast recovery diodes -Their characteristics and applications. Bipolar Junction transistors, Power MOSFETs P-Channel, N- Channel. IGBTs -Basic structure and working, Steady state and switching characteristics-Comparison of BJT, MOSFET and IGBT -Their applications. SCRs-Static and dynamic characteristics, Two transistor analogy.

### UNIT-II

**Turn on and turn off mechanisms** : BJT , Power MOSFET, IGBTs .SCR trigger circuits-R, RC and UJT triggering circuits. Triggering circuits for Single phase bridge rectifier and Choppers. Driver Circuits for MOSFET, IGBT and BJT. Protection of SCR's, Difference between forced and line commutation

#### UNIT-III

**Principles of controlled rectification** -Study of Single phase and three-phase half controlled and full controlled bridge rectifiers with R, RL, RLE loads. Effect of source inductances. Dual converters- circulating current mode and circulating current free mode-control strategies.

#### UNIT-IV

**Classification of Choppers** : Class A, B, C, D and E, Switching mode regulators-Study of Buck, Boost and Buck-Boost regulators, Cuk regulators . Principle of operation of Single phase bridge type Cyclo converters and their applications. Single phase AC Voltage Controllers with R, L and RL loads.

#### UNIT-V

**Principle of operation of Single phase Inverters** -Three phase bridge Inverters (180<sup>°</sup> and 120<sup>°</sup> modes)-voltage control of inverters-Single pulse width modulation- multiple pulse width modulation, sinusoidal pulse width modulation. Comparison of Voltage Source Inverters and Current source Inverters, Elementary Multilevel Inverters.

- 1. Singh.M.D and Khanchandani.K.B, Power Electronics, Tata McGraw Hill, 2nd Edition, 2006.
- 2. Rashid.M.H, Power Electronics Circuits Devices and Applications. Prentice Hall of India, 2003
- 3. M.S.Jamil Asghar, *Power Electronics*, Prentice Hall of India, 2004

4. Bimbra.P.S, Power Electronics, Third Edition, Khanna Publishers, 1999

5. Mohan, Undeland, Robbins, Power Electronics, John Wiley, 1996.

### DIGITAL ELECTRONICS AND LOGIC DESIGN (Common to IE & EEE)

Instruction	:	4 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	75 Marks

### **Objectives:**

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### UNIT-I

**Boolean Algebra:** Boolean Algebra and combinational logic AND,OR and NOT operations, Laws of Boolean Algebra, minimization of Boolean expressions, Truth tables and maps sum of products and product of sums -map method of reduction, incompletely specified functions multiple output minimization.

#### UNIT-II

**Binary arithmetic and circuits** -Half and Full adder- subtractor and Magnitude comparator, number complements-two's complement arithmetic, carry look ahead adder, decimal numbers and their codes, BCD and Excess-3 arithmetic, error detecting and error correcting codes.

### UNIT-III

**Tabular minimization:** Tabular minimization, Digital logic families and IC's, Characteristics of Digital IC's, Introduction to RTL, DTL, TTL, CMOS, ECL families, Details of TTL logic family -totem pole, open collector outputs. Wired AND operation, comparison of performance, TTL subfamilies, multiplexer and de-multiplexer, encoder and decoder, code converters, implementation of combinational logic using standard logic gates and multiplexers.

#### UNIT-IV

**Synchronous Sequential Circuits** -Basic latch circuit -debouncing switch -SR., JK, D and T flip-flops-truth table and excitation table conversion of flip-flops -ripple and synchronous counters up/down counter -general BCD counter- Counter decoding-shift registers, ring counters, modulo-N Counter.

#### UNIT-V

**Design of Digital Systems** -Concept of state. State diagram-design of counters Sequence detector and generators, state –space machines – Melay and Morry machine -Design procedure, using D, JK, T flip-flops -applications of registers -concepts of programmable, logic -PROM, PLA, PAL.

- 1. Donald Pleach / Albert Paul Malvino / Goutam saba, *Digital Principles and Applications*, McGraw- Hill, 2006.
- 2. Tocci & Widmer, Digital Systems, Pearson Education-Eighth Edition, 2003.
- 3. Morris Mano M., *Digital Design*, Prentice Hall of India, Third Edition, 2002.
- 4. B. Somnath Nair, Digital Electronics and Logic Design, Prentice Hall, India, 2002.
- 5. Kohavi --

### LINEAR INTEGRATED CIRCUITS (Common to IE & EEE)

Instruction	:	4 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	75 Marks

### **Objectives:**

- 1. To familiarize and able to understand Op-amps and its applications.
- 2. To understand the voltage regulators by using op-amps and active filters.

### UNIT-I

**Operational amplifiers** -Characteristics, open loop voltage gain, output impedance, input impedance, common mode rejection ratio -Offset balancing techniques -Slew rate, Frequency response -Stability, frequency compensation of Op-amp, basic applications -inverter summer, analog integrator, differentiator, current to voltage converter, voltage to current converter, voltage follower, ac amplifier.

### UNIT-II

Voltage limiter, clipper and clamper, precision rectifier-full wave and half wave, peak detector, comparator, zero crossing detector, Schmitt trigger, monostable, astable, bistable, multivi braters, multiplier, divider and difference amplifier instrumentation amplifier circuits using Op-amps.

### UNIT-III

Waveform generation using Op-amps- Sine, Square, Triangular and Quadrature oscillators, voltage controlled oscillator 555 timer functional diagram, operation as monostable and astable. phase locked loop, A/D - flash type, successive approximation and Dual slope type, D/ A- R-2R ladder type converters.

#### UNIT-IV

Series voltage regulator using Op-amp, shunt regulators using Op-amp, switching regulators using Op-amp, dual voltage regulator, fixed voltage regulators, dual tracking regulators, hybrid regulator, current sensing and current feedback protection, using 723.

#### UNIT-V

RC active filters, low pass, high band pass, band reject, notch, first order, second order transformation, state variable filter, switched capacitor filter, universal filter. Balanced modulator/ demodulator.

- 1. D.Roy Choudhury, *Linear Integrated Circuits*, Shail B.Jain, 3rd Edition, New Age International(P) Ltd., 2007.
- 2. Malvino Albert Paul, *Electronic Principles*, 7th Edition, Tata McGraw Hill, 2006
- 3. Coughlin and Driscoll, *Operational Amplifiers and Linear integrated Circuits*, 6th Edition, Prentice hall of India 2003.
- 4. David A. Bell, Operational Amplifiers and Linear ICs, PHI, 2003.
- 5. Gayakwad R.A, Op-Amps and Linear Integrated Circuits, 4th Edition, Prentice Hall of India, 2002.
- 6. William D. Stanley, *OP amps with LIC* pearson edition 2000.

### LINEAR CONTROL SYSTEMS (Common to IE & EEE)

Instruction	:	4/1 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	75 Marks

### **Objectives:**

- 1. To develop basic skills of utilizing mathematical tools needed to analyze and design classical linear control systems.
- 2. To understand and develop the state space representation of control systems.

## UNIT-I

**Open and Closed loop Systems**: Continuous time and discrete time control systems. Control system components, Error sensing devices, Potentiometers. Synchros, AC-DC servo motors-Block diagram representation, Transfer function and impulse response, Signal flow graphs.

### UNIT-II

**Time Response:** Types of Input, Transient response of second order system for step input. Time diagram specifications - Types of system- static error coefficients, Error Series-Routh-Hurwitz criterion of stability. Root Locus Technique- Typical systems analyzed by root locus technique-Effect of location of roots on system response PID Controller.

### UNIT-III

**Frequency Response Plots:** Bode Plots, Frequency domain specifications. : Mp, ώp for a second order system, Nyquist criterion for a stability, relative stability, gain and phase margin, Compensation: Cascade Compensation using Bode plots.

### UNIT-IV

**State Space Representation:** Concept of State, State Variable, State Models of linear time invariant systems. Derivation for state models from transfer functions and differential equations. State Transition matrix- Solution of State equations by time domain method. Observability and Controllability.

#### UNIT-V

**Discrete Control Analysis:** Introduction to signals and systems, The Z-transformation, digital control, advantages and disadvantages. Digital control system architecture. The discrete transfer function. Sample data system. Transfer function of sample data systems- Z-plane specifications of control system design Z-domain stability.

- 1. I.J.Nagrath, M.Gopal, *Control System Engineering*, New Age International (P) Limited Publishers, 5th Edition, 2007.
- 2. M.Gopal, Control Systems Principles and Design- Tata McGraw Hill, 2nd Edition, 2003.
- 3. K.Ogata, Modern Control Systems, 3rd Edition.PHI, 2000.
- 4. J.F.Franklin and J.D.Powell, Digital Control of Dynamic Systems, Addison Wesley, 1980.

## **ELECTRICAL MACHINES LAB -I**

Instruction	:	3 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	50 Marks

### **Objectives:**

- 1. To learn operation and performance characteristics of d.c. machines by conducting various experiments and tests practically.
- 2. To understand the operation and performance characteristics of transformers by conducting various experiments and tests.

## List of Experiments:

- 1. Magnetization characteristics and the speed Vs voltage curve of separately and self excited D.C. generator
- 2. Load characteristics of separately excited and Shunt Generators
- 3. Load characteristics of Compound generator
- 4. Performance characteristics of Series Motor
- 5. Performance characteristics of D.C. shunt motor
- 6. Performance characteristics of Compound motor
- 7. Separation of iron and friction losses and estimation of parameters in D.C. machines.
- 8. (a) Speed control of D.C. shunt motor by shunt field control and armature resistance control (b) Swinburne's Test
- 9. Separation of core losses in a Single Phase transformer
- 10. Open circuit and short circuit tests on a Single Phase transformer
- 11. Sumpner's test on two identical transformers
- 12. Estimation of efficiency of DC Machine by Hopkinson test.

#### Note: ATLEAST 10 EXPERIMENTS SHOULD BE CONDUCTED IN THE SEMESTER

## CONTROL SYSTEMS LAB (Common to IE & EEE)

Instruction	:	3 Periods per week
Duration of University Examination	:	3 Hours
Sessionals	:	25 Marks
University Examination	:	50 Marks

## List of Experiments:

- 1. Characteristics of D.C. and A.C. Servo motors.
- 2. Characteristics of Synchro Pair.
- 3. Frequency response of compensating networks.
- 4. Step response of second order system.
- 5. D.C.Positon Control System.
- 6. A.C.position Control System.
- 7. Closed loop P, PI and PID Controller.
- 8. Step response and Frequency response of a given plant.
- 9. Design of lag and lead compensation for the given plant.
- 10. ON/OFF Temperature Control systems.
- 11. Temperature control system using PID controllers
- 12. Level Control system

Note: ATLEAST 10 EXPERIMENTS SHOULD BE CONDUCTED IN THE SEMESTER.