

**Seventh Semester B.E. Degree Examination, Dec.09/Jan.10**  
**Control Engineering**

Time: 3 hrs

Max. Marks:100

**Note: Answer any FIVE full questions, selecting at least TWO questions from each part.**

**PART -- A**

1.
  - a. Explain open loop and closed loop control systems, with block diagrams. What are the advantages and disadvantages of a closed loop system over an open loop system? (10 Marks)
  - b. What are the requirements of a control system? Briefly explain. (05 Marks)
  - c. Draw the block diagram of proportional integral controller and explain. (05 Marks)
2.
  - a. Obtain the differential equations for the mechanical system shown in Fig.2(a). (10 Marks)

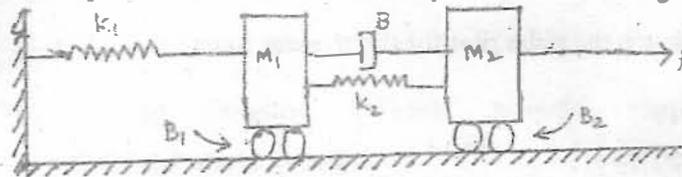


Fig.2(a)

- b. A thermometer is dipped in a vessel containing liquid at a constant temperature of  $\theta_1(t)$ . The thermometer has a thermal capacitance for storing heat as  $C$  and thermal resistance to limit heat flow as  $R$ . If the temperature indicated by the thermometer is  $\theta_2(t)$ , obtain the transfer function of the system. (10 Marks)
3.
  - a. Reduce the block diagram shown in Fig.3(a) to its simplest possible form and find its closed loop transfer function. (10 Marks)

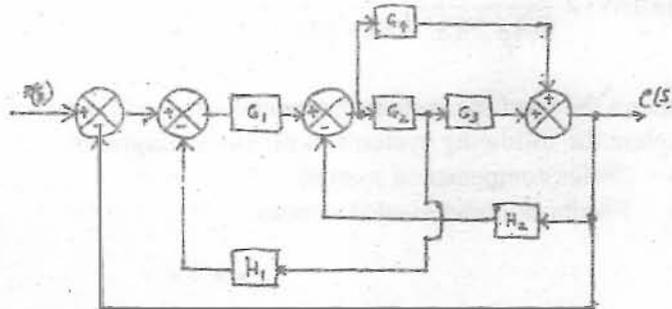


Fig.3(a)

- b. For the system shown in Fig 3(b) determine  $\frac{C(s)}{R(s)}$  using Mason's gain formula. (10 Marks)

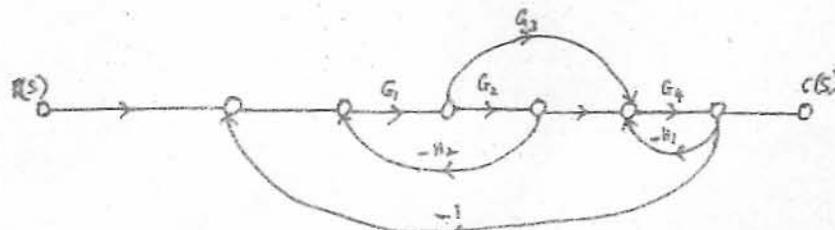


Fig.3(b).

- 4 a. A unity feedback system is characterized by an open loop transfer function

$$G(S) = \frac{10}{S^2 + 5S + 6}$$

Determine the following, when the system is subjected to a unit step input.

- i) Undamped natural frequency
- ii) Damping ratio
- iii) Peak overshoot
- iv) Peak time
- v) Setting time.

(12 Marks)

- b. Ascertain the stability of the system given by the characteristic equation,

$$S^6 + 3S^5 + 5S^4 + 9S^3 + 8S^2 + 6S + 4 = 0, \text{ by Routh Hurwitz criterion.}$$

(08 Marks)

### PART - B

- 5 a. Sketch the polar plot for the transfer function  $G(S) = \frac{10}{S(S+1)(S+2)}$ . (08 Marks)

- b. Apply Nyquist stability criterion to the system with transfer function

$$G(s)H(s) = \frac{4S+1}{S^2(1+S)(1+2S)}$$

and ascertain its stability. (12 Marks)

- 6 Sketch the Bode plot for  $G(s)H(s) = \frac{2}{S(S+1)(1+0.2S)}$ . Also obtain gain margin and phase margin and crossover frequencies. (20 Marks)

- 7 Sketch the root locus plot for the system, whose open loop transfer function is given by  $G(s)H(s) = \frac{K}{S(S+2)(S^2+8S+20)}$ . (20 Marks)

- 8 a. Explain the need for system compensation. List the types of compensators used. (10 Marks)

- b. Explain the following systems, with block diagrams.

- i) Series compensated system
- ii) Feedback compensated system.

(10 Marks)

\*\*\*\*\*